



*understanding
the ISO 10360-2
performance
standard®*



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Performance Standard - 03/01

Introduction

Process control and quality assurance in modern manufacturing depends more and more on Coordinate Measuring Machines (CMMs). Over the last 20 years CMMs have widely replaced the traditional inspection methods with gages and fixtures. Because of their flexibility CMMs can reduce investment costs while increasing inspection throughput.

In addition to standard geometrical features, precision CMMs equipped with highly accurate analog scanning technology can inspect special tight tolerance features such as gear and CAM profiles, roundness, and cylindricity. In the past inspection of this type would require single purpose, dedicated measuring devices.

High product quality does not only depend solely on the quality of the machine tools used for manufacturing. High product quality relies on the accuracy and repeatability of the instruments used for controlling the manufacturing process. For example, a low cost, low performance machining center in combination with a high precision CMM may still assure quality since only acceptable parts will pass inspection. Further a high quality machining center in combination with a low cost, low accuracy measuring device can not assure high quality product as a percentage of “out of tolerance” parts will inevitably pass inspection.

The selection of a suitable CMM therefore is a critical decision in a company’s quality control standards. This important selection is further complicated by the long life expectancy of CMMs compared to machine tools and by the wide array of CMM performance standards used in whole or part by various CMM manufacturers.

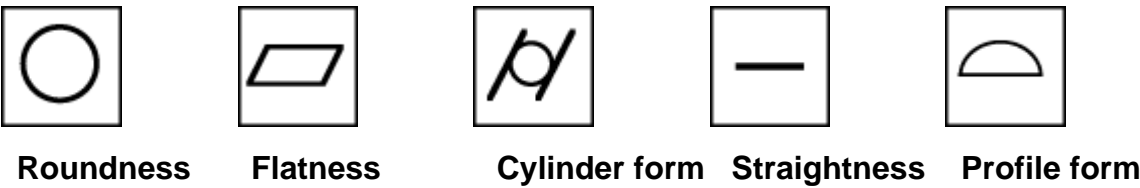
This brief guide focuses on the ISO 10360-2 performance standard utilized by Brown & Sharpe. The ISO 10360-2 is a comprehensive easy to understand standard that may be applied to real inspection applications to insure that an acceptable level of measurement uncertainty is considered for a given process. Specifically this guide includes:

- Overview of the ISO standard with an explanation of the test method.
- Discussion of the volumetric length measuring and volumetric probing uncertainties.
- Determining a measurement uncertainty to tolerance ratio.
- Analysis of the required CMM uncertainty and application examples.

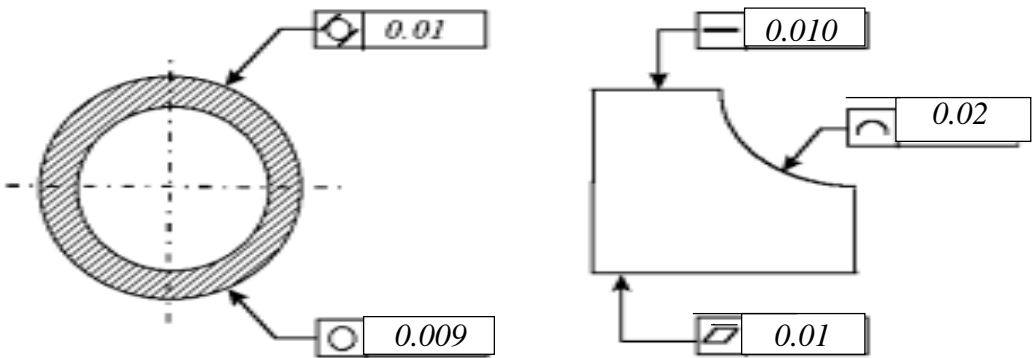
3. Form Tolerances

Refer to your part drawing and locate the tightest form tolerances. These include call outs for roundness, flatness, straightness, cylinder and profile form.

Example: Consider a Global Image 9158 with Analog probe, ISO R= 1.7 µm for the following application.



Drawing Tolerances



Determine the Tightest Tolerance: 0.009mm Roundness call-out

Determine the required Machine Measurement Uncertainty (based on a ratio of uncertainty to tolerance of 1:5)

Uncertainty to tolerance Ratio x (tolerance)
 $0.20 \times (\pm 9 \mu\text{m}) = 1.8 \mu\text{m}$

Check the selected machine uncertainty at this length:

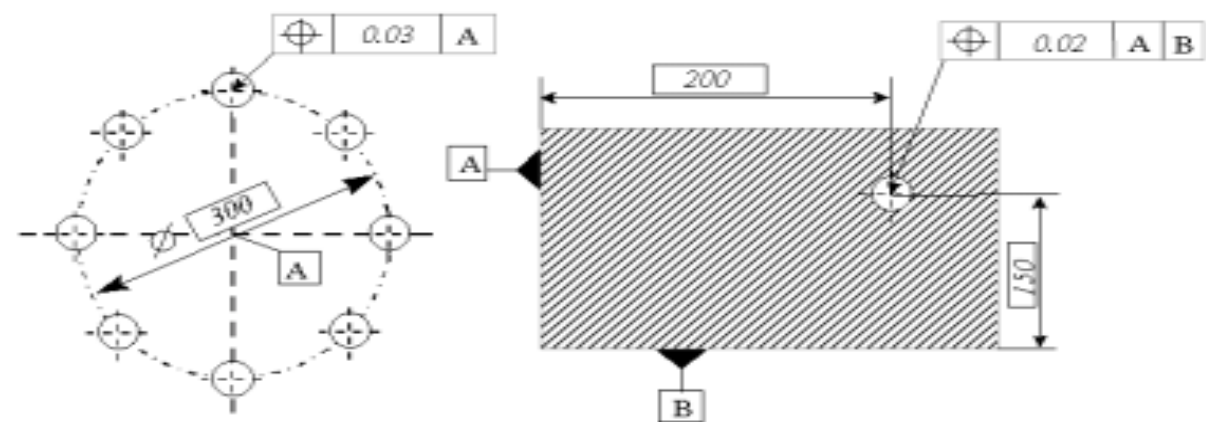
R (for Global Image 9158 with Analog Probe) = 1.7 µm

Since 1.7 µm > 1.8 µm ; This machine is acceptable for this application!

2. Position Tolerances

Refer to your part drawing and locate the tightest position tolerance. Since position tolerances usually define a tolerance diameter only the radius is used to determine the deviation from the nominal center. Again, note that because of the length dependency of volumetric uncertainty, a larger tolerance on a feature with a long distance to the datum may present more difficulty than a very tight tolerance with a short datum.

Example: Consider a Global Image 9158, ISO E = 1.9 + 3L/1000, for the following application.



NOTE: A Position tolerance of 20µm (circular) is equivalent to a tolerance of ± 10µm for the measurement!

For the 300 mm Circle Pattern	For the hole position
± 0.030mm or ± 30µm @ a length of 150mm 30 µm /300mm = 0.1µm/mm	± 0.020mm or ± 20µm @ a length of 200mm 20 µm /200mm = 0.1µm/mm
Since 0.1µm/mm < 0.2 µm/mm, the hole position presents the tighter tolerance.	

Determine the required Machine Measurement Uncertainty (based on a ratio of uncertainty to tolerance of 1:5)

Uncertainty to tolerance Ratio x (tolerance)
 $0.20 \times (\pm 20\mu\text{m} / 2) = 2.0 \mu\text{m}$

Check the selected machine uncertainty at this length:

$E \text{ (for Global Image 9158)} = 1.9 + 3 (200\text{mm})/1000 = 2.10 \mu\text{m}$

Since $2.10 \mu\text{m} > 2.0 \mu\text{m}$; A higher accuracy machine is required for this application!
Consider the Global Reference.

Overview of ISO 10360-2

ISO is an international organization that defines standards. The goal of the ISO 10360-2 standard is to define the performance verification of the CMM and its associated probe.

At the heart of the standard is the reliance on certified artifacts that by definition reproduce known values of a determined quantity. The artifacts utilized by the standard may include a series of gage blocks, step gauges and a precision sphere.



Series of Gage Blocks



Koba Step Gauge



Precision Sphere

It is important to note that for length measurements it is recommended that the longest standard be at least 66% of the longest measuring volume diagonal and that the shortest be no longer than 30mm.

There are two general uncertainties associated with the ISO standard; the first is the volumetric length measurement uncertainty (E) and the second is the volumetric probing uncertainty (R).

The Volumetric Length Measuring Uncertainty (E)

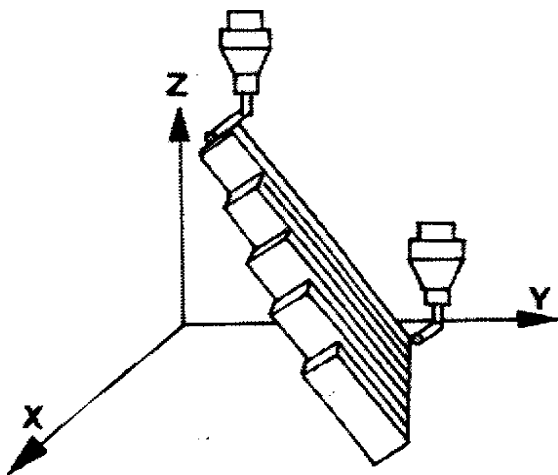
General Procedure

To verify the CMMs volumetric length measuring uncertainty a series of gage blocks or a step gauge is utilized.

The user selects 7 different locations (position and direction) within the machines measuring volume for the test. For each location five(5) material standards (lengths) are measured, three times each, for a total of 105 measurements.

7 different Locations x 5 different lengths x 3 repetitions = 105 Measurements

All 105 measurement results (100%) must be within the stated tolerance specified by the manufacturer.



Note:

The uncertainty of the artifacts must be considered. In general the artifact used should not have a length uncertainty (F) of greater than 20% of the CMM manufacturer’s stated volumetric length uncertainty (E).

If; $F < 0.2 \times E$, than the E stated by the manufacturer applies.
 $F > 0.2 \times E$, than $E = E_{\text{manufacturer}} + F$ applies.

Determine the Tightest Tolerance:

For the Diameter	For the distance
$\pm 0.030\text{mm}$ or $\pm 30 \text{ }\mu\text{m}$ @ a length of 300mm $30 \text{ }\mu\text{m}/300\text{mm} = 0.1 \text{ }\mu\text{m}/\text{mm}$	$\pm 0.020\text{mm}$ or $\pm 20 \text{ }\mu\text{m}$ @ a length of 50mm $20 \text{ }\mu\text{m}/50\text{mm} = 0.4 \text{ }\mu\text{m}/\text{mm}$
Since $0.1\mu\text{m}/\text{mm} < 0.4 \text{ }\mu\text{m}/\text{mm}$, the diameter is presents the tighter tolerance.	

Determine the required Machine Measurement Uncertainty (based on a ratio of uncertainty to tolerance of 1:5)
Uncertainty to tolerance Ratio x (tolerance)
 $0.20 \times (\pm 30 \text{ }\mu\text{m}) = 6.0 \text{ }\mu\text{m}$

Check the selected machine uncertainty at this length:

$E \text{ (for Global Status 9158)} = 3.0 + 4 (300\text{mm})/1000 = 4.2\text{mm}$

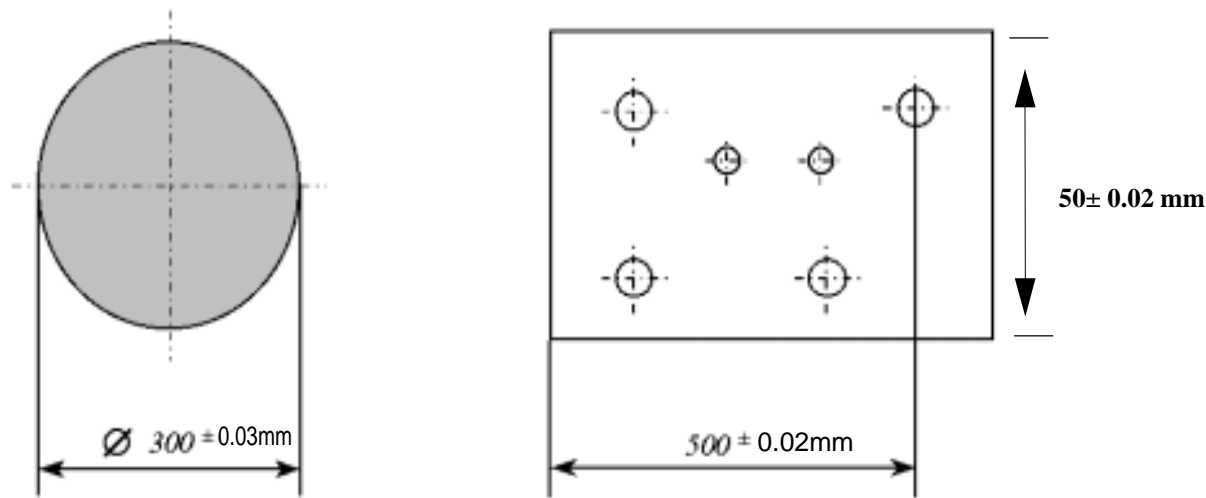
Since $4.2 \text{ }\mu\text{m} < 6.0 \text{ }\mu\text{m}$; This machine is acceptable for the application!

1. Diameter and Distance Tolerances

Refer to your part drawing and locate the diameter for distances with the tightest tolerance. Note that because of the length dependency of volumetric uncertainty, a larger tolerance on a very long feature may present more difficulty than a very tight tolerance on a small feature.

Next calculate the required machine volumetric length measurement uncertainty by applying the appropriate ratio of uncertainty to tolerance.

Example: Consider a Global Status 9158, ISO E = 3.0 + 4L/1000, for the following application.



The Volumetric Length Measuring Uncertainty (Continued)

Results

The volumetric length measuring uncertainty (E) is expressed as an equation of a line in micrometers (mm).

$E = \pm (A + L/K)$

where: *A* = Systemic or constant machine uncertainty in mm
L = Length of measurement in mm.
K = Length constant or slope of line.

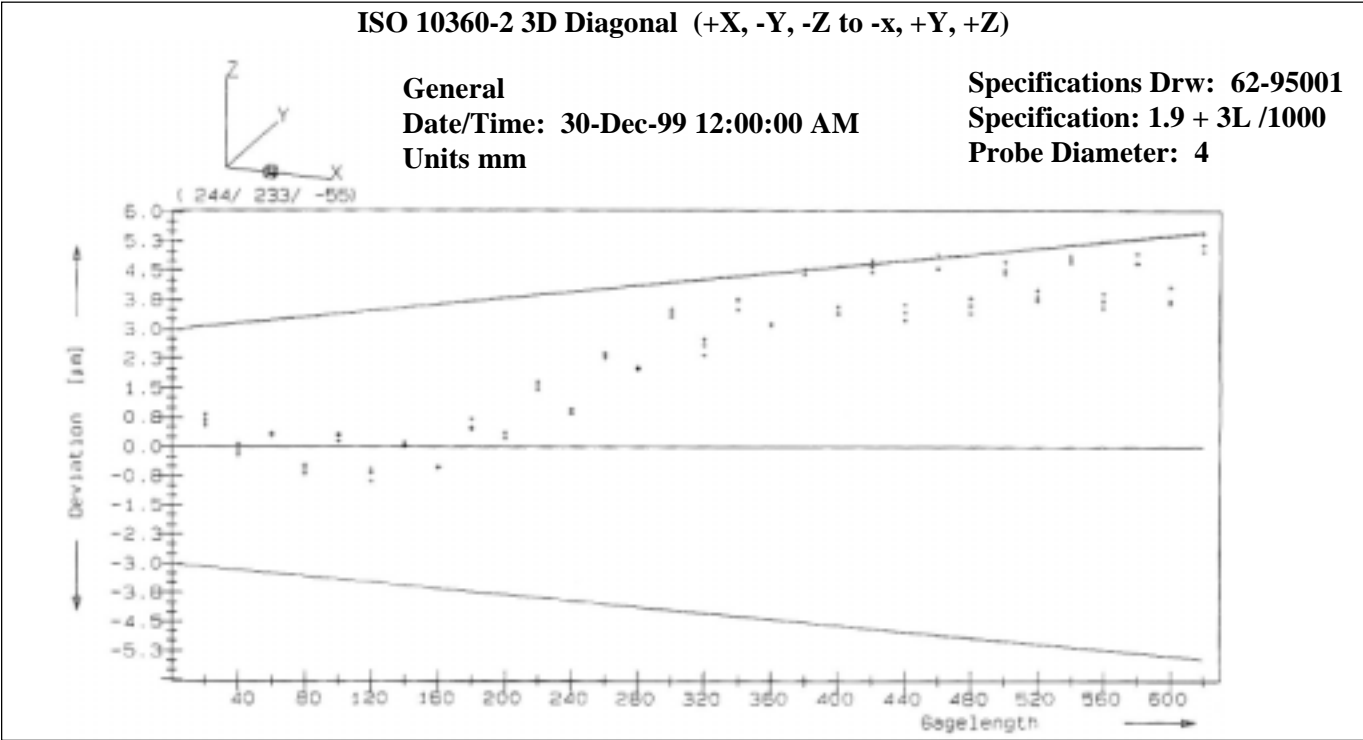
Example:

Given a machine E specification of $3.0 + L/250$. For a 200mm length measurement, anywhere in the machine volume, the associated uncertainty is:

$E = \pm 3.0 + (200/250) = \pm 3.0 + 0.8 = \pm 3.8\text{ mm}$

Sample output:

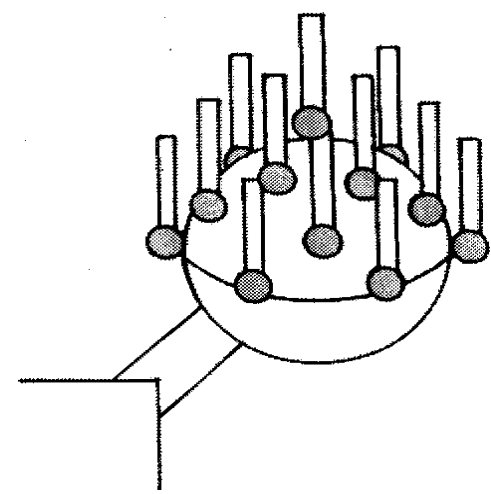
Machine Data Machine Name: Global C1 Machine Type: Bridge Controller Type: Common Machine Serial No: 12345	Parameters Positioning Ve.: 100 Contact Vel: 1.4 Acceleration: 100 Probe/Retract: 2	Software Operating System: Windows NT App. Software: XactQuindos Program Version: 1.0 Operator: J Dove
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The Volumetric Probing Uncertainty (R)

To verify the CMMs volumetric probing uncertainty a precision sphere is utilized. The sphere is required to be between 10mm and 50mm in diameter with certification for form and diameter.

The test consists of measuring 25 equally spaced points on the sphere hemisphere as illustrated below.



R is computed by adding the absolute values of the minimum and maximum deviation from the radial form. This result is typically reported in micrometers (mm). All 25 probings (100%) must be used in the calculation.

Analysis of the Required CMM Uncertainty

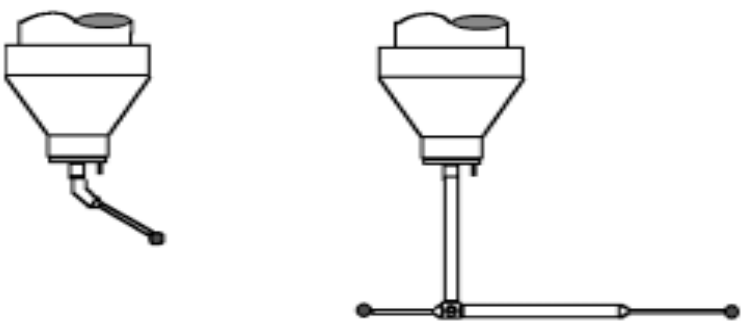
In nearly all applications, CMMs are used to inspect three general groups of features:

- 1. Diameter and Distance Tolerances
- 2. Position Tolerances
- 3. Form Tolerances

For each of these groups a determination of the acceptability of a given machine based on its ISO performance specification may be made. Examples follow for each case.

The Ratio of Machine Uncertainty to Tolerance

From your drawing tolerances the theoretically required ISO specifications “E” and “R” may be determined for a given application. However it is important to note that the manufacturer’s verified specifications may differ from actual workpiece measurements because of the use of probe extensions, long or thin probes, probe or stylus changes, environmental conditions, fixturing, etc.



E and R as specified

- probe pin
- fixed directly in probe head
- no extensions
- no rotation of probe head

E and R (Working condition):

- combination of several probe pins
- use of extensions
- rotation of probe head (Renishaw)
- probe change

Because of these differences it is generally accepted practice to apply a ratio of uncertainty to tolerance when calculating a required CMM specification. This ratio may vary widely depending on the factors described above, the complexity of the measurement task and the process itself. Typical ratios may range from 1:3 to 1:20 with 1:5 and 1:10 being most common.

Note:

In order to maintain a 1:5 ratio of CMM uncertainty to part tolerance the CMM data sheet specification should be 5 times more accurate than the tolerance being inspected.